

# Fast Approximate Matching of Programs for Protecting Libre/Open Source Software by Using Spatial Indexes

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# Libre/ Open Source Software

Protect Libre Software!

- FLOSS (Free/Libre Open Source Software).
- Copy-left. (GPL)
- Licensing Violations.
  - FSF and GPL-violations.
  - Using “strings” (binutils).
- Objective: Binary Program Matching.
  - Different Compilers/Obfuscators/Strings.
  - Return the top  $n$  most similar programs.
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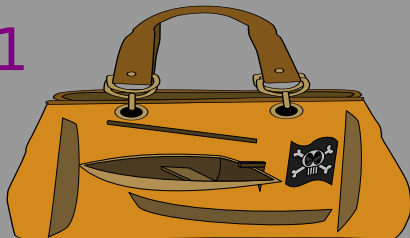
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Pirate Candidate

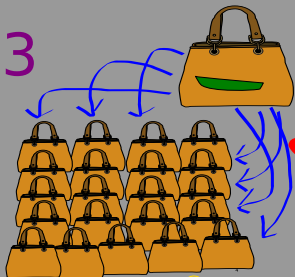


1



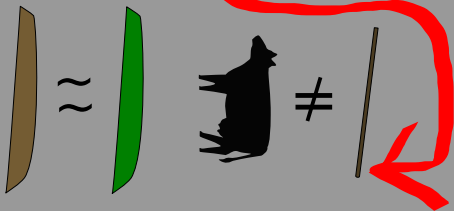
Program Fragments

3

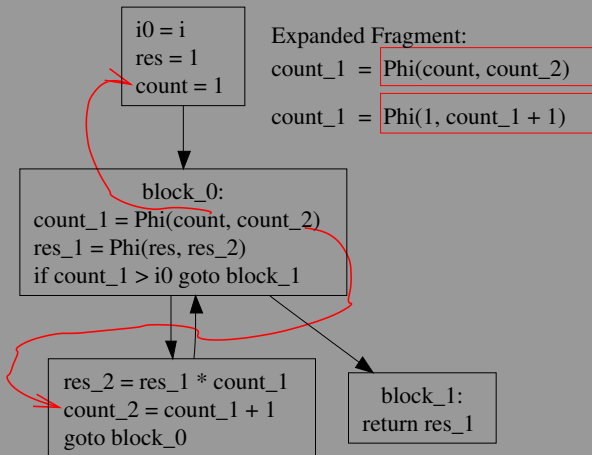


Ranking (IR)

2



Fragment Similarity  
(Stemming, "Normalization")



- Output: machine instruction trees.
- Matched with a distance function  $d$ .
- Ignore strings, function names.

# Fast Matching With Spatial Indexes

Select pivots, create a tuple based on  $d$ .

- Similarity search:
  - M-tree & friends: slow for  $d$ .
  - Vectors: B-tree (1 dim) or Spatial Index.
- Trees cannot be indexed directly.
- SMAP can be used to index them:
  - Select  $i$  pivots  $p_1 \dots p_i$  from the database.
  - Create a tuple  $(d(o, p_1), \dots, d(o, p_i))$  for each object  $o$ .
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# Synopsis of the Paper

Tackle performance and precision issues

- Matching one program was slow (3 days):
  - 10 hours (7x) (Tree parsing,  $d$ ).
  - 6 min (682x) (Spatial Index + SMAP).
- Previous ranking technique was not precise:
  - 22% of the time correct.
  - Improved to 96% (IR).
- Experiments:
  - DB:1670 programs.
  - Whole program matching. Max. obfuscation.
  - Query sets: (Default 1290 100%) (ZKM 290 100%) (Sandmark 280 96%)

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# Thank you!

## Contact Information

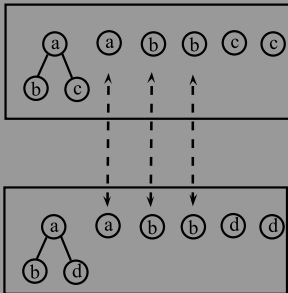
- Arnoldo Müller
  - arnoldoMuller@gmail.com
  - arnoldo@daisy.ai.kyutech.ac.jp
- For a tree (and anything else) matcher:
  - <http://obsearch.berlios.de/>



# Distance of Fragments

Example (Trees  $a(b, c)$  and  $a(b, d)$ )

Multi-set:



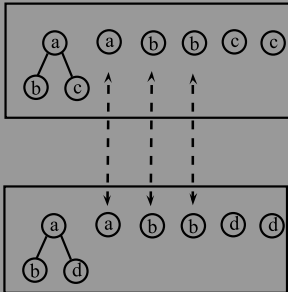
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# Matching Techniques Employed

## Spatial Indexes

- Spatial Indexes work in Euclidean spaces.
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## Sequential Search

- Tree creation is a heavy task.
  - Parse a string into a tree.
- Load all the trees into memory? **No!**
- Match the database against the query.
- Fragments of size differing in more than  $r$  ignored.

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# Program Ranking

Naive calculation replaced by information retrieval ranking

- For an application  $a$  and a query  $q$ :
- Naive calculation:  $\frac{|q \cap a|}{|a|}$  (NR).
  - “Rareness” of fragments not taken into account.
  - Distribution of the fragments in  $q$  and  $a$  ignored.
- Information retrieval techniques (IR).
  - Consider all this and more.
  - Employed Lucene (open source information retrieval software).



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Naive calculation replaced by information retrieval ranking

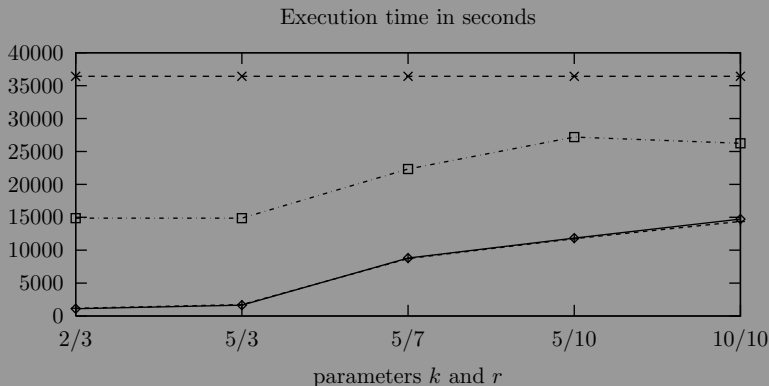
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# Performance

- Database size: 340000 fragments (30 MB).
- Query size: 1641 fragments (100kb).
- Prototype written in C++.
- *PRTREE*: Spatial Index.
- *SEQ*: Sequential search.
- $k$  : Retrieve closest  $k$  elements from DB.
- $r$  : For query  $q$  retrieve only if  $d(q, j) \leq r$  where  $j \in DB$ .

# Pruning by tree size

Improvement in sequential search.

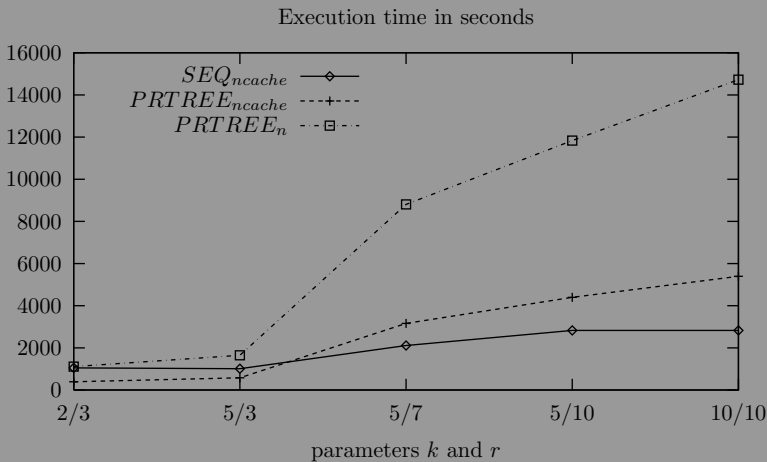


$PRTREE_n$  —◆—  
 $PRTREE$  - - - - -

$SEQ_n$  - - □ - -  
 $SEQ$  - - x - -

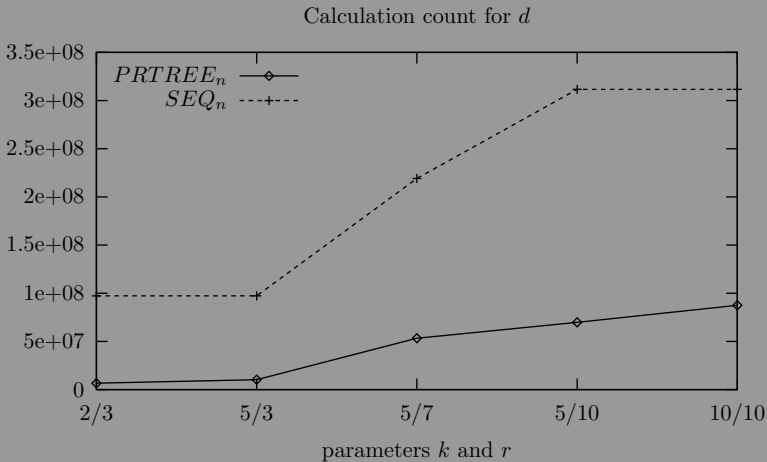
# Using cache

Using cache improves considerably performance



# Distance Computations

Distance computations are greatly reduced by *PRTREE*



# Triangle Inequality

Some notes:

- Exploit this:
  - $|d(x, y) - d(x, z)| \leq d(y, z)$
- $L_\infty$  for 2 vectors  $p$  and  $q$ :
  - $L_\infty = \max_i(|p_i - q_i|)$

# Preliminaries

- Programs downloaded from different sources.
- Query sets constructed:
  - *A*: byte-code as it was indexed.
  - *B*: Zelix Klass Master 4.5.
  - *C*: Sandmark 3.4.

Set	Transformation	# of Programs
A	default	1293
B	Zelix	290
C	Sandmark	281

# Overall Results for IR

- $\%X$ : accum. % of identifications for set  $X$ .
- $m(X)$ : number of matches found for set  $X$ .

$n$	$\%A$	$m(A)$	$\%B$	$m(B)$	$\%C$	$m(C)$
1	97.3	1259	96.8	281	87.5	246
2	98.8	19	99.6	8	90.7	9
3	99.3	7	100	1	92.1	4
4	99.8	6	—	—	93.5	4
5	99.9	1	—	—	94.6	3
6	99.9	0	—	—	94.6	0
7	99.9	0	—	—	95.0	1
8	99.9	0	—	—	95.3	1
9	100	1	—	—	95.7	1
10	—	—	—	—	96.0	1



# Overall Results for NR

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$n$	$\%A$	$m(A)$	$\%B$	$m(B)$	$\%C$	$m(C)$
1	18.2	236	4.4	13	9.6	27
2	33.2	194	15.8	33	12.8	9
3	49.1	206	25.5	28	14.2	4
4	59.0	127	33.4	23	16.0	5
5	65.1	80	40.0	19	17.7	5
6	69.9	61	45.5	16	18.1	1
7	73.7	50	51.0	16	19.5	4
8	77.4	48	54.1	9	20.6	3
9	80.6	41	58.2	12	21.3	2
10	83.6	38	62.4	12	22.7	4

# License Violation Detection Example

Embedded open source can be detected

- Query: “ccmtools”
- Returned:
  - antlr-2.7.6-1jpp.noarch
  - antlr-2.7.6-1jpp.noarch.rpm.jpackage
  - antlr
  - **ccmtools**
- “antlr” is actually embedded in ccmtools

# Next Steps!

- Expression normalization.
- Normalization Learning?
- Syntactically close but semantically different fragments.
- Other fragment extraction approaches.
- Detection of false negatives must be implemented.

# Summary

- A very simple and new technique has been proposed.
  - Fragment + Tree-distance + Ranking.
- Performance was substantially improved
  - Use of Spatial Indexes + SMAP.
- Reliability improved
  - By using information retrieval techniques.
- Possible applications:
  - Low-level duplicated functionality detection.

# Destroying our Technique

## Ways of attacking our method

- Disable the extraction of SSA:
  - Dynamic fragment extraction.
- Transform the Fragments:
  - Modify assignment expressions.
  - Many fragments must be changed/added (IR).
  - Some fragments cause more damage than others.
    - Depends on IR equations (private).
    - Depends on Database (frequency, private).

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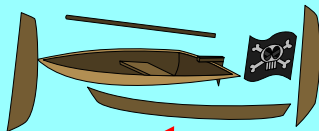
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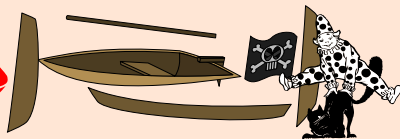
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## Original Program:

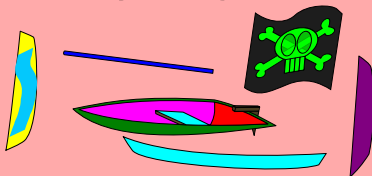


## Insert "garbage":



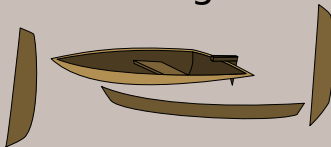
A lot of garbage is required.

## Modify Fragments



Has to destroy fragments considerably.

## Delete Fragments:



If they can, we can.  
Many must be removed.

# Modifying fragments

Make  $d > r$

- Fragments are trees.
- We use a range  $r$  to accept 2 fragments as similar:
  - $d(a, b) \leq r$  for  $a, b$  fragments.
- Change fragments so that  $d(a, b) > r$ .
  - Insert  $r$  nodes (easier).
  - Delete  $r$  nodes (if they can, we can).
  - Change  $r$  nodes for others (normalization).

# Destroying our technique (Summary)

Many fragments must be added/modified/deleted. (IR compensates)

- Fragment insertion:
  - New instructions must be added.
  - Many new fragments are required.
- Fragment deletion:
  - If they can, we can (static analysis).
- Fragment modification:
  - Insertion: requires  $r$  insertions.
    - Program can grow very much.
  - Deletion: requires  $r$  deletions.
    - if they can we can.
  - Replacement: term re-writing.

# Replacement

For Strings is already hard

- abcdef
- ahhhef (for  $r = 3$ )
- When alphabet (instructions for fragments) = 30:
  - $p(30, 3) = 24360$
  - $p(30, 7) = 1.026e + 10$
- For trees the possible permutations get bigger!
- Architectures with more instructions!

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